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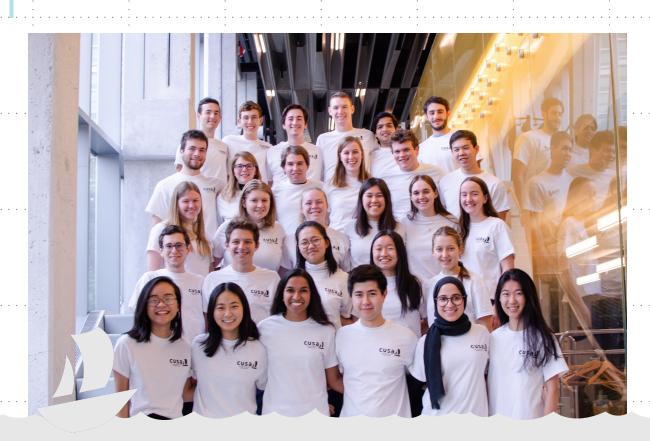


ABOUT THE TEAM



Starting as a research group led by Professor Andy Ruina in 2014, CUSail has grown into a student-led project team that is over 20 members strong.

CUSail offers students across many disciplines the opportunity to apply what they have been learning in the classroom to real world engineering problems of tomorrow. Using cutting-edge technology and advanced mechanical design, our team is exploring the uncharted waters that is the field of autonomous sailboats.



THE COMPETITION



Our boat will compete at the SailBot International Robotic Sailboat Regatta in Newburyport, MA in the summer of 2020. The competition is comprised of seven challenges over five days against American and international collegiate teams.

THE EVENTS

NAVIGATION TEST Navigate around a series of buoys

FLEET RACE Manual-control regatta race

DISTANCE RACE 6 hours of navigating a square course

STATION KEEPING Hold a GPS position on the water

COLLISION

React quickly to avoid new obstacles

AVOIDANCE

PAYLOAD Navigate with a 2 kg weight



LONG-TERM GOALS



SAIL THE LENGTH OF CAYUGA LAKE

The first goal in our series of long-term goals is to sail from the southern end of Cayuga Lake in Ithaca, NY to the northern end in Cayuga, NY. Cayuga Lake is just under 40 miles long, and we would be able to test our navigation algorithm and sailing endurance on a larger scale.

OF AUTONOMOUS SAILBOATS

CUSail's ultimate goal is to create a fleet of autonomous sailboats. We want to perfect our mechanical design so that we can easily build many sailboats at a low cost. The boats could monitor weather trends in different parts of the world or track whale migration patterns.

CROSS THE ATLANTIC OCEAN

We want to sail across the Atlantic Ocean from New York to Portugal to demonstrate that our boat is robust enough to survive ocean and weather conditions, and prove that our navigation algorithm can successfully navigate with such a long planned route.



NAVIGATION



SUBTEAM

Devin Dean, Everett White, Adityavardhan
Agrawal, Aidan Chalnick, Jamie Poole,
Courtney McBeth, **Diane Sutyak**, Alan Hsiao,
Fabrizio Casanova Alaimo, Vivian Jiang,
Rachel Zhou, William Slacedo
Not pictured: Mahika Kudluqi



The Navigation subteam works with all electronics and software on our boat. Our boat's autonomous capabilities rest on two major pillars: gathering data from its environment and executing calculated decisions. An array of sensors allow detection of global position, wind direction, and boat direction. The Navigation subteam uses data from these sensors to devise an algorithm, allowing our boat to navigate. The subteam also designs sub-systems for land communication with our boat, data logging, and efficient power distribution.

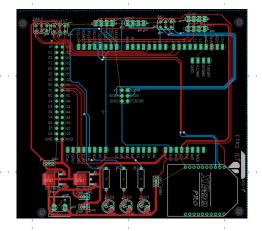


NAVIGATION DESIGN



2019-2020

- Arduino Due microcontroller with Atmel SAM3X8E processor
- Lightware SF11 LiDAR Sensor
- Inertial Measurement Unit to calculate boat direction
- PixyCam for obstacle detection
- Xbee-Pro S3B modules for communication between the boat and basestation (PC)



PCB Layout



MECHANICAL

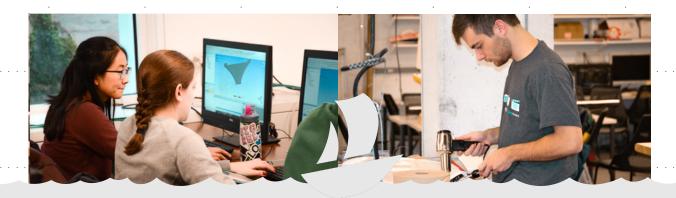


SUBTEAM

Rafael Gottlieb, Chris Kutil, Alex Merrill, Nick
Allen, **Katherine Gray**, Mary Essex, Julianna
Seifert, Halle Buescher, Claudia Buchard,
Aleksandra Nasiukiewicz, Jennifer Lee
Not Pictured: Philip Ayoub, Claire BeckBelaman



The Mechanical subteam is responsible for designing and manufacturing all of the mechanical components of the boat. The team members work on tasks like redesigning the deck and hull to increase waterproofing reliability and gain skills such as rapid prototyping, machining, and composite and mold making. Working on the mechanical team involves constant problem solving and hands-on skills as well as an advanced technical understanding of the boat.



MECHANICAL DESIGN² 2019-2020

RIGID AIRFOIL

SAIL

Designed like an airplane wing, provides additional lift

MOTOR-DRIVEN

MAST ROTATION

Provides control and optimal angle of attack even without a rudder

CARBON FIBER

DECK AND HULL

Reduced weight and increased strength

TAIL AIRFOIL

Steers the boat without introducing additional drag forces

RUDDERLESS

DESIGN

Unique tail airfoil design provides directional stability without a

ALUMINUM FIN

KEEL

1.3 meter seamless keel provides superior ballast support

BUSINESS SUBTEAM



Meghana Gavirneni, Mary Essex, Jackson Kopitz, **Crystal Wu**, Rachel Han, Nada Attia, Tomas Engquist



The Business subteam is a multi-disciplinary team that manages funding and operations for the team. We create the team's budget and manage team finances. The Business subteam also works to obtain all sponsorships from corporations and individuals. We design the team website, brand, and merchandise in addition to being responsible for team photo and video documentation and administrative tasks.



SPONSORSHIP



CONTRIBUTOR LEVELS

DINGHY

- Personal thank you note
- Logo on website

MOTORBOAT

- All above benefits
- Small logo sticker on sail

YACHT

\$500+

\$5000+

- All above benefits
- \$1000+ IVIE
- Medium logo sticker on sail
 - Team Resume booklet

AIRCRAFT CARRIER

- All above benefits
- Large logo sticker on sail
- CUSail sponsored information session on campus

CONTRIBUTIONS ARE TAX



DONATION FORM



Donor Information	Please mail forms	and
Name / Organization:	checks, made ou "Cornell University" v a memo "CUŞail"	ıt to vith
Organization Address:	Kae-Lynn Wil 141 Upson Cornell Univer Ithaca, NY 14	Hall rsity
Telephone Number: E-Mail Address:	If you have questions, ple	ease
Organization Website: Donation Information	Jackson Ko Full Team L jsk363@cornell. Crystal	ead <u>edu</u>
Monetary Donation Amount: \$ Fair Market Value of Gift in Kind: \$	Business Team L <u>cw683@cornell.</u>	.ead
*Donations to CUSail are tax-deductible. Do you require a charitable donation receipt? [] Yes [] N	3	
Signature:	Date:	

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THANK YOU FOR YOUR SUPPORT!



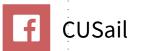
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Cornell Engineering



35 SOLIDWORKS

CONTACT US





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